

# Expander Graphs and Their Applications (XX)

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# Constraints

## Definition

Let  $V = \{v_1, \dots, v_n\}$  be a set of variables, and let  $\Sigma$  be a finite alphabet. A  $q$ -ary constraint  $c = (C, i_1, \dots, i_q)$  consists of

- ▶ a  $q$ -tuple of indices  $i_1, \dots, i_q \in [n]$ ,
- ▶ and a subset  $C \subseteq \Sigma^q$  of “acceptable” values.

An assignment  $\mathcal{A} : V \rightarrow \Sigma$  *satisfies*  $c$  if

$$(\mathcal{A}(v_{i_1}), \dots, \mathcal{A}(v_{i_q})) \in C.$$

The formula  $X_3 \vee \neg X_7 \vee X_9$  can be viewed as a constraint  $(C, 3, 7, 9)$  with

$$\{(1, 0, 0), (1, 0, 1), (1, 1, 0), (1, 1, 1), (0, 0, 0), (0, 0, 1), (0, 1, 1)\}.$$

# Constraint Satisfaction Problems (CSP)

CSP

*Input:* A system (i.e., set)  $\mathcal{C}$  of constraints over a set of variables  $V$  and a finite alphabet  $\Sigma$ .

*Problem:* Is there an assignment  $\mathcal{A} : V \rightarrow \Sigma$  that satisfies every constraint?

## 3COLORABILITY as CSP

### Lemma

3COLORABILITY *is reducible to* CSP.

### Proof.

Let  $\Sigma := \{0, 1, 2\}$ . Given a graph  $G = (V, E)$ , we identify  $V$  with the set of variables.

For each edge  $e \in E$  with end vertices  $v_i$  and  $v_j$ , we introduce a constraint

$$c_e := (C_e, i, j)$$

where

$$C_e := \{(a, b) \in \Sigma^2 \mid a \neq b\}.$$

Then

$G$  is 3-colorable  $\iff$  there is an assignment satisfying  $\{C_e \mid e \in E\}$ .



Let  $\mathcal{C}$  be a set of constraints. We define

unsat( $\mathcal{C}$ ) := the smallest fraction of  
*unsatisfied* constraints of  $\alpha$  under any assignment

$$= \min_{\mathcal{A} \text{ an assignment}} \frac{|\{c \in \mathcal{C} \mid \mathcal{A} \text{ satisfies } c\}|}{|\mathcal{C}|}.$$

$\mathcal{C}$  is satisfiable  $\iff$  unsat( $\mathcal{C}$ ) = 0;

$\mathcal{C}$  is not satisfiable  $\iff$  unsat( $\mathcal{C}$ )  $\geq \frac{1}{|\mathcal{C}|}$ .

Let  $q \in \mathbb{N}$ ,  $\epsilon > 0$ , and  $\Sigma$  be a finite alphabet.

GAP-CSP $_{q,\Sigma,\epsilon}$

*Input:* A set  $\mathcal{C}$  of  $q$ -ary constraints over the alphabet  $\Sigma$  such that *either*  $\text{unsat}(\mathcal{C}) = 0$  *or*  $\text{unsat}(\mathcal{C}) \geq \epsilon$ .

*Problem:* Decide whether  $\mathcal{C}$  is satisfiable.

### Theorem

NP = PCP( $\log n, 1$ ) if and only if for some  $\epsilon > 0$  the problem GAP-CSP $_{q,\Sigma,\epsilon}$  is NP-hard (for some  $q \geq 2$  and  $|\Sigma| \geq 2$ ).

## Constraint Graphs and Operations on Them

# Constraint Graph

## Definition

$G = \langle (V, E), \Sigma, \mathcal{C} \rangle$  is a constraint graph, if

1.  $(V, E)$  is an undirected graph (possibly with selfloops and multi-edges), i.e., *the underlying graph* of  $G$ .
2. The set  $V$  is also viewed as a set of variables assuming values over alphabet  $\Sigma$ .
3. Each edge  $e \in E$  carries a constraint  $c(e) \subseteq \Sigma^2$  and  $\mathcal{C} = \{c(e) \mid e \in E\}$ . A constraint  $c(e)$  is said to be satisfied by  $(a, b)$  if  $(a, b) \in c(e)$ .

## Remark.

- ▶ *The above definition is the rephrase of a CSP with each constraint being binary.*
- ▶ *Sometimes, we also use  $G$  to refer to  $(V, E)$ .*



## unsat

An assignment is a mapping  $\sigma : V \rightarrow \Sigma$ .

For a constraint graph  $G = \langle (V, E), \Sigma, \mathcal{C} \rangle$  and an assignment  $\sigma$ :

$$\underline{\text{unsat}}_{\sigma}(G) := \Pr_{\substack{e \in E \text{ with} \\ \text{endvertices } u \text{ and } v}} [(\sigma(u), \sigma(v)) \notin c(e)]$$

Then

$$\underline{\text{unsat}}(G) := \min_{\sigma} \text{unsat}_{\sigma}(G)$$

We have already seen:

### Theorem

Given a constraint graph  $G = \langle (V, E), \Sigma, \mathcal{C} \rangle$  with  $|\Sigma| = 3$ , it is NP-hard to decide whether  $\underline{\text{unsat}}(G) = 0$ .

## unsat Amplification

Let  $G = \langle (V, E), \Sigma, \mathcal{C} \rangle$  be a constraint graph. Then

$$G \text{ is satisfiable} \iff \text{unsat}(G) = 0$$

$$G \text{ is not satisfiable} \iff \text{unsat}(G) \geq \frac{1}{|\mathcal{C}|} = \frac{1}{|E|}.$$

*Our goal:* In polynomial time, compute from  $G$  another constraint graph  $G^*$  such that

$$G \text{ is satisfiable} \iff \text{unsat}(G^*) = 0$$

$$G \text{ is not satisfiable} \iff \text{unsat}(G^*) \geq \alpha.$$

# Main Theorem

## Definition

For every constraint graph  $G = \langle (V, E), \Sigma, \mathcal{C} \rangle$ , let

$$\underline{\text{size}}(G) := |V| + |E|.$$

## Theorem

There exists a  $\Sigma_0$  such that the following hold.

For every finite alphabet  $\Sigma$  there exist two constants  $C_\Sigma > 0$  and  $0 < \alpha_\Sigma < 1$  and a *polynomial time algorithm*  $\mathbb{A}_\Sigma$  such that for every constraint graph  $G$ , the algorithm  $\mathbb{A}_\Sigma$  computes a constraint graph  $G'$  such that

- ▶  $\text{size}(G') \leq C_\Sigma \cdot \text{size}(G)$ .
- ▶ If  $\text{unsat}(G) = 0$ , then  $\text{unsat}(G') = 0$ .
- ▶ If  $\text{unsat}(G) \neq 0$ , then  $\text{unsat}(G') \geq \min(2 \cdot \text{unsat}(G), \alpha_\Sigma)$ .

## Main Theorem (cont'd)

Let  $\Sigma$  be a finite alphabet.

Consider the following algorithm  $\mathbb{G}_\Sigma$  with input a constraint graph  $G = \langle (V, E), \Sigma, \mathcal{C} \rangle$ .

1.  $G_0 = \langle (V_0, E_0), \Sigma_0, \mathcal{C}_0 \rangle \leftarrow \mathbb{A}_\Sigma(G)$ .
2. **for**  $i = 1$  **to**  $\log |\mathcal{C}_0|$  **do**
3.  $G_i \leftarrow \mathbb{A}_{\Sigma_0}(G)$ .
4. Output  $G_{\log |\mathcal{C}_0|}$ .

### Theorem

- ▶  $\text{unsat}(\mathbb{G}_\Sigma(G)) \geq \alpha_{\Sigma_0}$ .
- ▶ For every  $i \in [\log |\mathcal{C}_0|]$ ,

$$\text{size}(G_i) \leq C_{\Sigma_0}^i \cdot \text{size}(G_0) = C_{\Sigma_0}^{\log |\mathcal{C}_0|} \cdot \text{size}(G_0) = \text{size}(G)^{O(1)}.$$

- ▶  $\mathbb{G}_\Sigma$  is a polynomial time algorithm.

# Graph Powering

Fix some  $d \in \mathbb{N}$ .

Let  $G = \langle (V, E), \Sigma, \mathcal{C} \rangle$  be a constraint graph with  $(V, E)$  being  $d$ -regular, and  $t \in \mathbb{N}$ .

Recall, a sequence  $(u_0, u_1, \dots, u_t)$  is a  $t$ -step walk in  $G$  if there is an edge between  $u_{i-1}$  and  $u_i$  for all  $i \in [t]$ .

Then we will define the following  $t$ -th power of  $G$

$$\underline{G^t} := \langle (V, E^t), \Sigma^{d^{\lceil t/2 \rceil}}, \mathcal{C}^t \rangle$$

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1. The vertices of  $G^t$  are the same as  $G$ . The number of edges in  $E^t$  between  $u$  and  $v$  is the number of  $t$ -step walks from  $u$  to  $v$  in  $G$ .
2. The alphabet of  $G^t$  is  $\Sigma^{d^{\lceil t/2 \rceil}}$ : Let

$$\Gamma(u) := \{u' \in V \mid u = u_0, u_1, \dots, u_{\lceil t/2 \rceil} = u' \text{ is a walk in } G\}.$$

Then  $|\Gamma(u)| \leq d^{\lceil t/2 \rceil}$  and *by choosing some canonical order*, a value  $a \in \Sigma^{d^{\lceil t/2 \rceil}}$  can be interpreted as an assignment  $a : \Gamma(u) \rightarrow \Sigma$ . One might think of this value as describing  $u$ 's opinion of its neighbor's values.

3. The constraint  $C(e)$  associated with an edge  $e \in E^t$  with end vertices  $u$  and  $v$  contains those pairs  $a, b \in \Sigma^{d^{\lceil t/2 \rceil}}$  if: There is an assignment  $\sigma : \Gamma(u) \cup \Gamma(v) \rightarrow \Sigma$  that satisfies every constraint  $c(e) \in \mathcal{C}$  where  $e \in E \cap (\Gamma(u) \times \Gamma(v))$ , and such that

$$\text{for all } u' \in \Gamma(u) \text{ and } v' \in \Gamma(v), \quad \sigma(u') = a_{u'} \text{ and } \sigma(v') = b_{v'}$$

where  $a_{u'}$  is the value  $a$  assigns  $u'$ , and  $b_{v'}$  the value  $b$  assigns to  $v'$ .

## Amplification Lemma

Clearly  $\text{unsat}(G) = 0$  implies  $\text{unsat}(G^t) = 0$ . What about the other direction?

### Lemma

Let  $0 < \lambda < d$  and  $|\Sigma|$  be constants. Then there exists a constant  $\beta_2 = \beta_2(\lambda, d, |\Sigma|) > 0$  such that for every  $t \in \mathbb{N}$  and for every  $d$ -regular constraint graph  $G$  with a selfloop on each vertex and  $\lambda(G) \leq \lambda$ ,

$$\text{unsat}(G^t) \geq \beta_2 \cdot \sqrt{t} \cdot \min\left(\text{unsat}(G), \frac{1}{t}\right).$$

What we have lost:

- ▶ degree  $d \rightarrow d^t$ ;
- ▶ size  $|V| + |E| \rightarrow |V| + d^{t-1} \cdot |E|$ .

# Preprocessing Lemma

## Lemma

There exist constant  $0 < \lambda < d$  and  $\beta_1 > 0$  such that any constraint graph  $G$  can be transferred into a constraint graph  $G' := \text{prep}(G)$  such that

- ▶  $G'$  is  $d$ -regular with selfloops and  $\lambda(G') \leq \lambda < d$ .
- ▶  $G'$  has the same alphabet as  $G$  and  $\text{size}(G') = O(\text{size}(G))$ .
- ▶  $\beta_1 \cdot \text{unsat}(G) \leq \text{unsat}(G') \leq \text{unsat}(G)$ .



# Alphabet Reduction

## Lemma

There exist a constant  $\beta_3 > 0$ , an alphabet  $\Sigma_0$ , and a linear time algorithm  $\mathbb{C}$  such that for every constraint graph  $G = \langle (V, E), \Sigma, \mathcal{C} \rangle$  the algorithm  $\mathbb{C}$  computes a constraint graph  $G'$  over the alphabet  $\Sigma_0$  such that

- ▶  $\text{size}(G') \leq c_\Sigma \cdot \text{size}(G)$ , where  $c_\Sigma$  is a constant only depending on  $\Sigma$ .
- ▶ and  $\beta_3 \cdot \text{unsat}(G) \leq \text{unsat}(G') \leq \text{unsat}(G)$ .

# Main Theorem (again)

## Theorem

There exists a  $\Sigma_0$  such that the following hold.

For every finite alphabet  $\Sigma$  there exist two constants  $C_\Sigma > 0$  and  $0 < \alpha_\Sigma < 1$  and a *polynomial time algorithm*  $\mathbb{A}_\Sigma$  such that for every constraint graph  $G$ , the algorithm  $\mathbb{A}_\Sigma$  computes a constraint graph  $G'$  such that

- ▶  $\text{size}(G') \leq C_\Sigma \cdot \text{size}(G)$ .
- ▶ If  $\text{unsat}(G) = 0$ , then  $\text{unsat}(G') = 0$ .
- ▶ If  $\text{unsat}(G) \neq 0$ , then  $\text{unsat}(G') \geq \min(2 \cdot \text{unsat}(G), \alpha_\Sigma)$ .

## Proof of the Main Theorem

Let

$$H_1 := \text{prep}(G)$$

$$H_2 := (H_1)^t$$

$$G' := H_2 \longrightarrow G'$$

where

$$t := \left[ \left( \frac{2}{\beta_1 \cdot \beta_2 \cdot \beta_3} \right)^2 \right]$$

and the arrow is the the alphabet reduction.

## Proof of the Main Theorem (cont'd)

Then

$$\begin{aligned}\text{unsat}(G') &\geq \beta_3 \cdot \text{unsat}(H_2) \\ &\geq \beta_3 \cdot \beta_2 \cdot \sqrt{t} \cdot \min\left(\text{unsat}(H_1), \frac{1}{t}\right) \\ &\geq \beta_3 \cdot \beta_2 \cdot \sqrt{t} \cdot \min\left(\beta_1 \cdot \text{unsat}(G), \frac{1}{t}\right) \\ &\geq \min(2 \cdot \text{unsat}(G), \alpha)\end{aligned}$$

where

$$\alpha := \frac{\beta_3 \cdot \beta_2}{\sqrt{t}}.$$

□