



## Design and Analysis of Algorithms (XVIX)

Steiner tree and TSP

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We will present constant factor algorithms for **metric Steiner tree**, and the rest of the problem can be reduced to this case.

## STEINER TREE

Given an undirected graph  $G = (V, E)$  with nonnegative edge costs and whose vertices are partitioned into two sets, **required** and **Steiner**, find a minimum cost tree in  $G$  that contains all the **required vertices** and any subset of the **Steiner vertices**.

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With a restriction to instances in which the edge costs satisfy the triangle inequality, i.e.,  $G$  is a complete undirected graph, and for any three vertices  $u$ ,  $v$ , and  $w$ ,

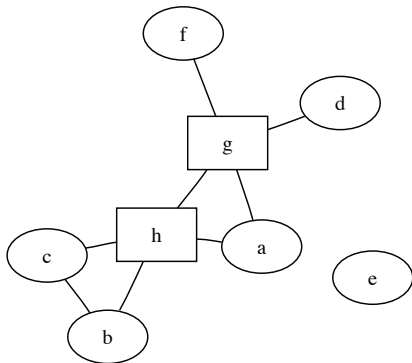
$$\text{cost}(u, v) \leq \text{cost}(u, w) + \text{cost}(v, w)$$

named the **metric Steiner tree problem**.



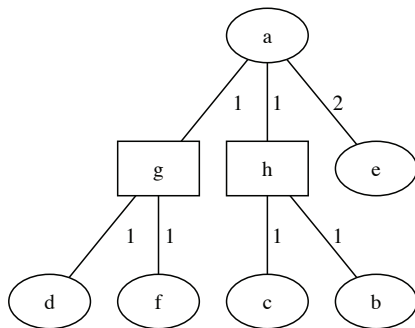
## An Example

If we have a **Steiner graph**, with the **cost 1** to the points connected by an edge, and cost **2** otherwise.



## An Example

The optimal one:



## Theorem

There is an *approximation factor* preserving reduction from the Steiner tree problem to the metric Steiner tree problem.

# Approximation Factor Preservation

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- Therefore, the cost of an **optimal solution** in  $I'$  does not exceed the cost of an **optimal solution** in  $I$ .

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Next, given a **Steiner tree**  $T'$  in  $I'$ , we will show how to obtain, in **polynomial time** a Steiner tree  $T$  in  $I$  of at most the same cost.

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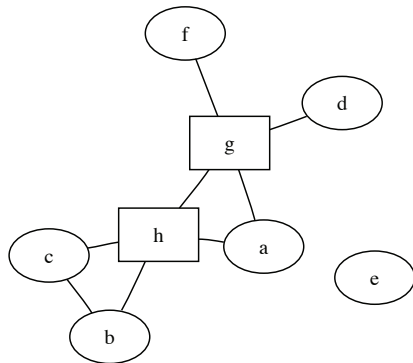
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- Clearly, in this subgraph, all the required vertices are connected. However, this subgraph may, in general, contain cycles.
- If so, remove edges to obtain tree  $T$ . This completes the approximation factor preserving reduction.

## Algorithm

Let  $R$  denote the set of **required vertices**. It is easy to verify that a **minimum spanning tree** on  $R$  is a **feasible solution** for this problem.

## An Example

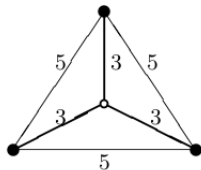
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## A Counterexample

The cost of MST may not be **optimal**:



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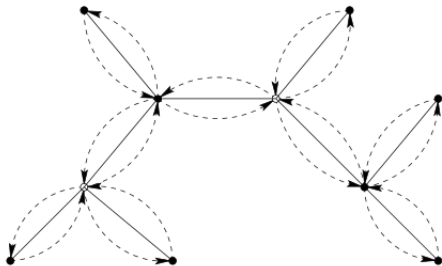
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Consider a Steiner tree of cost  $OPT$ . By doubling its edges we obtain an Eulerian graph connecting all vertices of  $R$  and, possibly, some Steiner vertices.

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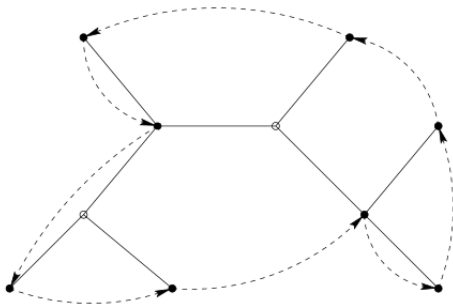
Find an **Euler tour** of this graph, for example by traversing the edges in **DFS** (depth first search) order:



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The cost of this Euler tour is  $2 \cdot \text{OPT}$ . Next obtain a **Rudrata cycle** on the vertices of  $R$  by traversing the Euler tour and **short-cutting** Steiner vertices and previously visited vertices of  $R$ :





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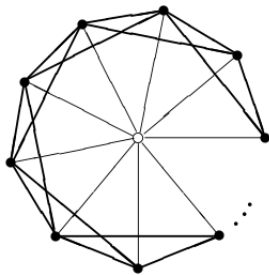
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If we delete one edge of this **Rudrata cycle**, we obtain a path that spans  $R$  and has cost at most  $2 \cdot \text{OPT}$ .

This path is also a **spanning tree** on  $R$ . Hence, the MST on  $R$  has cost at most  $2 \cdot \text{OPT}$ .

## Tightness of the Analysis

Consider a graph with  $n$  required vertices and one Steiner vertex. An edge between the Steiner vertex and a required vertex has cost 1, and an edge between two required vertices has cost 2:





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- Interestingly, TSP cannot be approximated within any **polynomial bounded ratio**.
- For any **polynomial time computable** function  $\alpha(n)$ , TSP cannot be approximated within a factor of  $\alpha(n)$ , unless **P = NP**.

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- The *distance* between cities  $u$  and  $v$  is 1 if  $\{u, v\}$  is an *edge* of  $G$  and  $1 + \alpha$  otherwise, for some  $\alpha > 1$  to be *determined*.
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If  $G$  has a *RUDRATA CYCLE*, then the same cycle is also a tour within the *budget* of the TSP *instance*.

If  $G$  has no *RUDRATA CYCLE*, then there is no solution: the cheapest possible TSP tour has cost at least  $n + \alpha$ .

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We will describe a reduction from **RUDRATA CYCLE PROBLEM** (which is **NP-completeness**) to TSP problem.

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Assign a weight of  $1$  to edges of  $G$ , and a weight of  $\alpha(n) \cdot n$  to nonedges, to obtain  $G'$ .

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If we restrict ourselves to graphs in which edge costs satisfy triangle inequality, i.e., consider **metric TSP**, the problem **remains NP-complete**, but it is **no longer hard to approximate**.

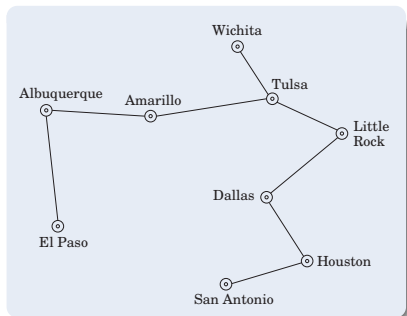
## TSP on Metric Space

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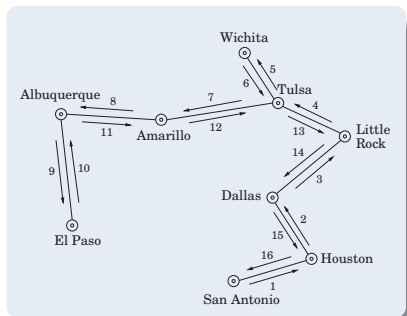
Removing any edge from a **traveling salesman tour** leaves a path through all the vertices, which is a **spanning tree**.

Therefore, **TSP cost**  $\geq$  cost of **this path**  $\geq$  **MST cost**



## TSP on Metric Space

If we can use each edge **twice**, then by following the shape of the **MST** we end up with a tour that visits **all** the cities, some of them **more than once**.



## TSP on Metric Space

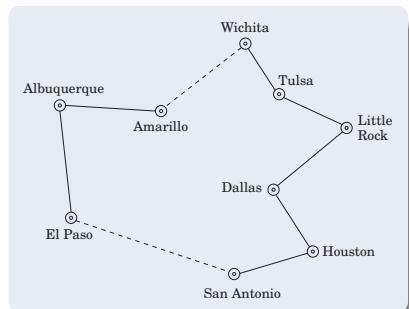
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By the **triangle inequality**, these **bypasses** can only make the overall tour shorter.



## A Simple Factor 2 Algorithm

Consider the following algorithm:

- 1 Find an **MST**,  $T$  of  $G$
- 2 Double every edge of the **MST** to obtain an **Eulerian graph**.
- 3 Find an **Eulerian tour**,  $\mathcal{T}$ , on this graph.
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The above algorithm is a factor 2 approximation algorithm for **metric TSP**.

# Analysis

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Combining these inequalities we get that

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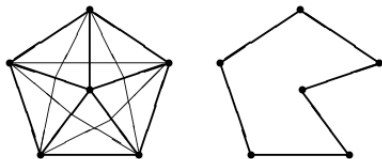
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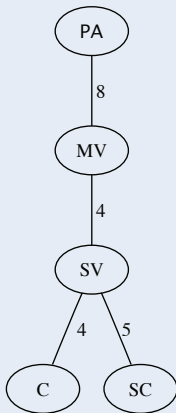




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	C	MV	PA	SC	SV
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Thus, we only need to be concerned about the vertices of odd degree in the **MST**.

Let  $V'$  denote the set of vertices of **odd degree** in the MST. Now, if we add to the MST a **minimum cost perfect matching** on  $V'$ , every vertex will have an **even degree**, and we get an **Eulerian graph**.

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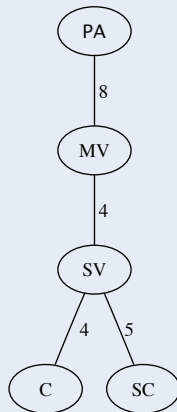
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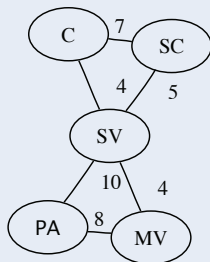


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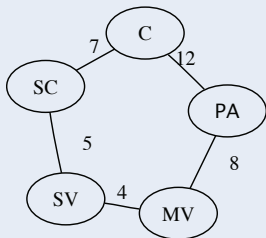
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### *Proof.*

Consider an *optimal TSP tour* of  $G$ , say  $\tau$ .

Let  $\tau'$  be the tour on  $V'$  obtained by *short-cutting*  $\tau$ . By the *triangle inequality*,  $\text{cost}(\tau') \leq \text{cost}(\tau)$ .

## Lemma

Let  $V' \subseteq V$ , such that  $|V'|$  is *even*, and let  $M$  be a *minimum cost perfect matching* on  $V'$ . Then,  $\text{cost}(M) \leq \text{OPT}/2$ .

### *Proof.*

Consider an *optimal TSP tour* of  $G$ , say  $\tau$ .

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Thus, the *cheaper* of these matchings has cost  $\leq \text{cost}(\tau')/2 \leq \text{OPT}/2$ . Hence the *optimal matching* also has cost at most  $\text{OPT}/2$ .

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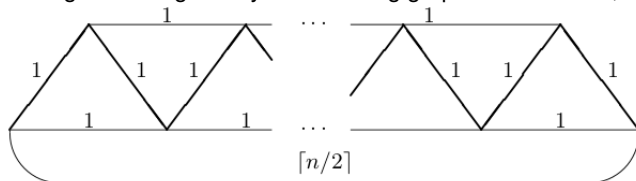
The cost of the Euler tour,

$$\text{cost}(\mathcal{T}) \leq \text{cost}(T) + \text{cost}(M) \leq \text{OPT} + \frac{1}{2}\text{OPT} = \frac{3}{2}\text{OPT}$$

Using the *triangle inequality*,  $\text{cost}(\mathcal{C}) \leq \text{cost}(\mathcal{T})$ , and the theorem follows.

## A Tight Example

A **tight example** for this algorithm is given by the following graph on  $n$  vertices, with  $n$  odd.



Thick edges represent the MST found in **step 1**. This MST has only two odd vertices, and by adding the edge joining them we obtain a traveling salesman tour of cost  $(n - 1) + n/2$ . In contrast, the **optimal tour** has cost  $n$ .

# A Better Algorithm?

## A Better Algorithm?

Finding a better approximation algorithm for metric TSP is currently one of the outstanding open problems in this area. Many researchers have conjectured that an **approximation factor** of  $4/3$  may be achievable.





## Referred Materials

- Content of this lecture comes from Chapter 3 in [Vaz04].