

## Algorithm Design V

Divide and Conquer II

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## Complex Number

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z=r(\cos \theta+i \sin \theta)=r e^{i \theta}
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- length: $r=\sqrt{a^{2}+b^{2}}$.
- angle: $\theta \in[0,2 \pi)$.
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Basic arithmetic:

- $-z=(r, \theta+\pi)$.
- $\left(r_{1}, \theta_{1}\right) \times\left(r_{2}, \theta_{2}\right)=\left(r_{1} r_{2}, \theta_{1}+\theta_{2}\right)$.
- If $z$ is on the unit circle (i.e., $r=1$ ), then $z^{n}=(1, n \theta)$.


## The $n$-th Complex Roots of Unity

Solutions to the equation $z^{n}=1$

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For $n$ is even:

- These numbers are plus-minus paired.
- Their squares are the ( $n / 2$ )-nd roots of unity.


## Complex Conjugate

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The angle between two vectors $u=\left(u_{0}, \ldots, u_{n-1}\right)$ and $v\left(v_{0}, \ldots, v_{n-1}\right)$ in $\mathbb{C}^{n}$ is just a scaling factor times their inner product

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The above quantity is maximized when the vectors lie in the same direction and is zero when the vectors are orthogonal to each other.

## The Fast Fourier Transform

## Polynomial multiplication

If $A(x)=a_{0}+a_{1} x+\ldots+a_{d} x^{d}$ and $B(x)=b_{0}+b_{1} x+\ldots+b_{d} x^{d}$, their product

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C(x)=c_{0}+c_{1} x+\ldots+c_{2 d} x^{2 d}
$$

has coefficients

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c_{k}=a_{0} b_{k}+a_{1} b_{k-1}+\ldots+a_{k} b_{0}=\sum_{i=0}^{k} a_{i} b_{k-i}
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where for $i>d$, take $a_{i}$ and $b_{i}$ to be zero.

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Q: Can we do better?

## An alternative representation

Fact: A degree- $d$ polynomial is uniquely characterized by its values at any $d+1$ distinct points.

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Its value at any given point $z$ is just $A(z)$ times $B(z)$.
Therefore, polynomial multiplication takes linear time in the value representation.

## The algorithm

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Evaluation
Compute $A\left(x_{0}\right), A\left(x_{1}\right), \ldots, A\left(x_{n-1}\right)$ and $B\left(x_{0}\right), B\left(x_{1}\right), \ldots, B\left(x_{n-1}\right)$ ．

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Compute $C\left(x_{k}\right)=A\left(x_{k}\right) B\left(x_{k}\right)$ for all $k=0, \ldots, n-1$.

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Multiplication
Compute $C\left(x_{k}\right)=A\left(x_{k}\right) B\left(x_{k}\right)$ for all $k=0, \ldots, n-1$.
Interpolation
Recover $C(x)=c_{0}+c_{1} x+\ldots+c_{2 d} x^{2 d}$

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Evaluating a polynomial of degree $d \leq n$ at a single point takes $O(n)$, and so the baseline for $n$ points is $\Theta\left(n^{2}\right)$.

The Fast Fourier Transform (FFT) does it in just $O(n \log n)$ time, for a particularly clever choice of $x_{0}, \ldots, x_{n-1}$.

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First idea, we pick the $n$ points,

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\pm x_{0}, \pm x_{1}, \ldots, \pm x_{n / 2-1}
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then the computations required for each $A\left(x_{i}\right)$ and $A\left(-x_{i}\right)$ overlap a lot, because the even power of $x_{i}$ coincide with those of $-x_{i}$.

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We need to split $A(x)$ into its odd and even powers, for instance

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3+4 x+6 x^{2}+2 x^{3}+x^{4}+10 x^{5}=\left(3+6 x^{2}+x^{4}\right)+x\left(4+2 x^{2}+10 x^{4}\right)
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More generally

$$
A(x)=A_{e}\left(x^{2}\right)+x A_{o}\left(x^{2}\right)
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where $A_{e}(\cdot)$, with the even-numbered coefficients, and $A_{o}(\cdot)$, with the odd-numbered coefficients, are polynomials of degree $\leq n / 2-1$.

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Given paired points $\pm x_{i}$, the calculations needed for $A\left(x_{i}\right)$ can be recycled toward computing $A\left(-x_{i}\right)$ :

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If we could recurse, we would get a divide-and-conquer procedure with running time

$$
T(n)=2 T(n / 2)+O(n)=O(n \log n)
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## How to choose $n$ points?

Aim: To recurse at the next level, we need the $n / 2$ evaluation points $x_{0}^{2}, x_{1}^{2}, \ldots, x_{n / 2-1}^{2}$ to be themselves plus-minus pairs.

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By continuing in this manner, we eventually reach the initial set of $n$ points: the complex $n t h$ roots of unity, that is the $n$ complex solutions of the equation

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## The $n$-th complex roots of unity

Solutions to the equation $z^{n}=1$

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For $n$ is even:

- These numbers are plus-minus paired.
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$\operatorname{FFT}(A, \omega)$
input : coefficient reprentation of a polynomial $A(x)$ of degree $\leq n-1$, where $n$ is a power of 2 ; $\omega$, an $n$-th root of unity
output: value representation $A\left(\omega^{0}\right), \ldots, A\left(\omega^{n-1}\right)$
if $\omega=1$ then return $A(1)$;
express $A(x)$ in the form $A_{e}\left(x^{2}\right)+x A_{o}\left(x^{2}\right)$;
call FFT ( $A_{e}, \omega^{2}$ ) to evaluate $A_{e}$ at even powers of $\omega$; call $\operatorname{FFT}\left(A_{o}, \omega^{2}\right)$ to evaluate $A_{o}$ at even powers of $\omega$; for $j=0$ to $n-1$ do
compute $A\left(\omega^{j}\right)=A_{e}\left(\omega^{2 j}\right)+\omega^{j} A_{o}\left(\omega^{2 j}\right)$;
end
return $\left(A\left(\omega^{0}\right), \ldots, A\left(\omega^{n-1}\right)\right)$;


## Interpolation

FFT moves from coefficients to values in time just $O(n \log n)$, when the points $\left\{x_{i}\right\}$ are complex $n$-th roots of unity $\left(1, \omega, \omega^{2}, \ldots, \omega^{n-1}\right)$.

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We will see that the interpolation can be computed by

$$
\langle\text { coefficients }\rangle=\frac{1}{n} \mathrm{FFT}\left(\langle\text { values }\rangle, \omega^{-1}\right)
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Vandermonde matrices also have the distinction of being quicker to invert than more general matrices, in $O\left(n^{2}\right)$ time instead of $O\left(n^{3}\right)$.

However, using this for interpolation would still not be fast enough for us..

In linear algebra terms, the FFT multiplies an arbitrary $n$-dimensional vector, which we have been calling the coefficient representation, by the $n \times n$ matrix.

$$
M_{n}(\omega)=\left[\begin{array}{ccccc}
1 & 1 & 1 & \ldots & 1 \\
1 & \omega & \omega^{2} & \ldots & \omega^{n-1} \\
& & \vdots & & \\
1 & \omega^{j} & \omega^{2 j} & \ldots & \omega^{(n-1) j} \\
& & \vdots & & \\
1 & \omega^{n-1} & \omega^{2(n-1)} & \ldots & x^{(n-1)(n-1)}
\end{array}\right]
$$

Its $(j, k)$-th entry (starting row- and column-count at zero) is $\omega^{j k}$

## Interpolation resolved

The columns of $M$ are orthogonal to each other, which is often called the Fourier basis.

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Inversion formula

$$
M_{n}(\omega)^{-1}=\frac{1}{n} M_{n}\left(\omega^{-1}\right)
$$

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Recall that the angle between two vectors $u=\left(u_{0}, \ldots, u_{n-1}\right)$ and $v\left(v_{0}, \ldots, v_{n-1}\right)$ in $\mathbb{C}^{n}$ is just a scaling factor times their inner product

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u \cdot v^{*}=u_{0} v_{0}^{*}+u_{1} v_{1}^{*}+\ldots+u_{n-1} v_{n-1}^{*}
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where $z^{*}$ denotes the complex conjugate of $z$.

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The above quantity is maximized when the vectors lie in the same direction and is zero when the vectors are orthogonal to each other.

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- Take the inner product of of any columns $j$ and $k$ of matrix $M$,

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1+\omega^{j-k}+\omega^{2(j-k)}+\ldots+\omega^{(n-1)(j-k)}
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This is a geometric series with first term 1, last term $\omega^{(n-1)(j-k)}$, and ratio $\omega^{j-k}$.

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- If $j=k$, then it evaluates to $n$.


## Corollary

$M M^{*}=n I$, i.e.,

$$
M_{n}^{-1}=\frac{1}{n} M_{n}^{*}
$$

## The definitive FFT algorithm

The FFT takes as input a vector $a=\left(a_{0}, \ldots, a_{n-1}\right)$ and a complex number $\omega$ whose powers $1, \omega, \omega^{2}, \ldots, \omega^{n-1}$ are the complex $n$－th roots of unity．

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The product of $M_{n}(\omega)$ with vector $a=\left(a_{0}, \ldots, a_{n-1}\right)$, a size-n problem, can be expressed in terms of two size- $n / 2$ problems: the product of $M_{n / 2}\left(\omega^{2}\right)$ with $\left(a_{0}, a_{2}, \ldots, a_{n-2}\right)$ and with $\left(a_{1}, a_{3}, \ldots, a_{n-1}\right)$.

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This divide-and-conquer strategy leads to the definitive FFT algorithm, whose running time is $T(n)=2 T(n / 2)+O(n)=O(n \log n)$.

## The general FFT algorithm

```
FFT (a,\omega)
```

input : An array $a=\left(a_{0}, a_{1}, \ldots, a_{n-1}\right)$ for $n$ is a power of $2 ; \omega$, an $n$-th root of unity output: $M_{n}(\omega) a$

```
if }\omega=1\mathrm{ then return }a\mathrm{ ;
( }\mp@subsup{s}{0}{},\mp@subsup{s}{1}{},\ldots,\mp@subsup{s}{n/2-1}{\prime})=\operatorname{FFT}((\mp@subsup{a}{0}{},\mp@subsup{a}{2}{},\ldots,\mp@subsup{a}{n-2}{}),\mp@subsup{\omega}{}{2})
( s
for j=0 to n/2-1 do
    r}\mp@subsup{r}{j}{=s}\mp@subsup{s}{j}{}+\mp@subsup{\omega}{}{j}\mp@subsup{s}{j}{\prime}
    r r+n/2}=\mp@subsup{s}{j}{}-\mp@subsup{\omega}{}{j}\mp@subsup{s}{j}{\prime}
end
return (ro, r},\mp@code{, ., , rn-1);
```


## Top 10 algorithms of the 20th century

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1946: The Metropolis Algorithm
1947: Simplex Method
1950: Krylov Subspace Method
1951: The Decompositional Approach to Matrix Computations
1957: The Fortran Optimizing Compiler
1959: QR Algorithm
1962: Quicksort
1965: Fast Fourier Transform

1977: Integer Relation Detection
1987: Fast Multipole Method

Homework

## Homework

- Assignment 2 (1 week). Exercises 2.13, 2.19, 2.22, and 2.28.

