

# **Design and Analysis of Algorithms (X)**

Simple Unit-Capacity Networks

Guoqiang Li School of Software



# **Bipartite Matching**

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# Matching



### Definition

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Maximum matching. Given a graph G, find a max-cardinality matching.



## **Bipartite Matching**



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A graph *G* is bipartite if the nodes can be partitioned into two subsets *L* and *R* such that every edge connects a node in *L* with a node in *R*.

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Bipartite matching. Given a bipartite graph  $G = (L \cup R, E)$ , find a max-cardinality matching.



### **Max-Flow Formulation**



### Formulation.

- Create digraph  $G' = (L \cup R \cup \{s, t\}, E')$ .
- Direct all edges from L to R, and assign infinite (or unit) capacity.
- Add unit-capacity edges from *s* to each node in *L*.
- Add unit-capacity edges from each node in *R* to *t*.





#### Theorem

1-1 correspondence between matchings of cardinality k in G and integral flows of value k in G'.



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*Proof.*  $\Rightarrow$ 



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### *Proof.* $\Rightarrow$

- Let M be a matching in G of cardinality k.
- Consider flow *f* that sends 1 unit on each of the *k* corresponding paths.
- f is a flow of value k.



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- Consider M = set of edges from L to R with f(e) = 1.



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#### Proof. ⇐

- Let f be an integral flow in G' of value k.
- Consider M = set of edges from L to R with f(e) = 1.
  - each node in *L* and *R* participates in at most one edge in *M*.
  - |M| = k: apply flow-value lemma to cut  $(L \cup \{s\}, R \cup \{t\})$ .



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Can solve bipartite matching problem via max-flow formulation.

### Proof.

- Integrality theorem  $\Rightarrow$  there exists a max flow  $f^*$  in G' that is integral.
- 1-1 correspondence  $\Rightarrow f^*$  corresponds to max-cardinality matching.

# Quiz 1



What is running time of Ford–Fulkerson algorithms to find a max-cardinality matching in a bipartite graph?

```
A. O(|E| + |V|)
B. O(|E||V|)
C. O(|E||V|^2)
D. O(|E|^2|V|)
```

# Quiz 2



Which max-flow algorithm to use for bipartite matching?

- **A.** Ford–Fulkerson:  $O(|E| \cdot |V| \cdot C)$ .
- **B.** Capacity scaling:  $O(|E|^2 \cdot \log C)$ .
- **C.** Shortest augmenting path:  $O(|E|^2|V|)$ .
- **D.** Dinitz' algorithm:  $O(|E||V|^2)$ .



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Q. When does a bipartite graph have a perfect matching?

Structure of bipartite graphs with perfect matchings.

- Clearly, we must have |L| = |R|.
- Which other conditions are necessary?
- Which other conditions are sufficient?



Notation.

Let S be a subset of nodes, and let N(S) be the set of nodes adjacent to nodes in S.



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#### Notation.

Let S be a subset of nodes, and let N(S) be the set of nodes adjacent to nodes in S.

Observation. If a bipartite graph  $G = (L \cup R, E)$  has a perfect matching, then  $|N(S)| \ge |S|$  for all subsets  $S \subseteq L$ .

*Proof.* Each node in S has to be matched to a different node in N(S).





### Theorem (Frobenius 1917, Hall 1935)

Let  $G = (L \cup R, E)$  be a bipartite graph with |L| = |R|. Then, graph G has a perfect matching iff  $|N(S)| \ge |S|$  for all subsets  $S \subseteq L$ .



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*Proof.*  $\Rightarrow$ 

This was the previous observation.





Proof. ⇐



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Suppose *G* does not have a perfect matching.



### Proof. $\Leftarrow$

Suppose *G* does not have a perfect matching.

Formulate as a max-flow problem and let (A, B) be a min cut in G'.



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Define  $L_A = L \cap A, L_B = L \cap B, R_A = R \cap A$ .



### Proof. $\Leftarrow$

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Define  $L_A = L \cap A, L_B = L \cap B, R_A = R \cap A$ .

 $\operatorname{cap}(A,B) = |L_B| + |R_A| \Rightarrow |R_A| < |L_A|$ 

Min cut can't use  $\infty$  edges  $\Rightarrow N(L_A) \subseteq R_A$ .

 $|N(L_A)| \le |R_A| < |L_A|.$ 

Choose  $S = L_A$ .

# **Bipartite Matching**



Problem. Given a bipartite graph, find a max-cardinality matching.

year	worst case	technique	discovered by
1955	O( E  V )	augmenting path	Ford–Fulkerson
1973	$O\left( E  V ^{1/2}\right)$	blocking flow	Hopcroft–Karp, Karzanov
2004	$O( V ^{2.378})$	fast matrix multiplication	Mucha-Sankowsi
2013	$\tilde{O}\left( E ^{10/7}\right)$	electrical flow	Madry
20xx	???		

# Quiz 3



Which of the following are properties of the graph G = (V, E)?

- **A.** *G* has a perfect matching.
- **B.** Hall's condition is satisfied:  $|N(S)| \ge |S|$  for all subsets  $S \subseteq V$ .
- C. Both A and B.
- D. Neither A nor B.






Problem. Given an undirected graph, find a max-cardinality matching.

## **Nonbipartite Matching**



Problem. Given an undirected graph, find a max-cardinality matching.

- Structure of nonbipartite graphs is more complicated.
- But well understood. [Tutte-Berge formula, Edmonds-Gallai]
- Blossom algorithm: O(n<sup>4</sup>). [Edmonds 1965]
- Best known:  $O(mn^{1/2})$ . [Micali–Vazirani 1980, Vazirani 1994]



### Hackathon problem.

- Hackathon attended by *n* Harvard students and *n* Princeton students.
- Each Harvard student is friends with exactly k > 0 Princeton students; each Princeton student is friends with exactly k Harvard students.
- Is it possible to arrange the hackathon so that each Princeton student pair programs with a different friend from Harvard?



Mathematical reformulation. Does every *k*-regular bipartite graph have a perfect matching?

Example. Boolean hypercube.





### Theorem

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### Theorem

Every k-regular bipartite graph G has a perfect matching.

Proved by Hall's Marriage Theorem, DIY!

## Hackathon Problem: Another Proof



### Proof.

- Size of max matching = value of max flow in G'.
- · It is easy to construct the following flow



• The value of flow f is  $n \Rightarrow G'$  has a perfect matching.

Hall's Theorem by Max-Flow



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## Definition

A flow network is a simple unit-capacity network if:

- Every edge has capacity 1.
- Every node (other than *s* or *t*) has exactly one entering edge, or exactly one leaving edge, or both.



Property. Let *G* be a simple unit-capacity network and let *f* be a 0–1 flow. Then, residual network  $G_f$  is also a simple unit-capacity network.



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Shortest-augmenting-path algorithm.

- Normal augmentation: length of shortest path does not change.
- Special augmentation: length of shortest path strictly increases.

## Theorem (Even–Tarjan 1975)

In simple unit-capacity networks, Dinitz'algorithm computes a maximum flow in  $O(|E||V|^{1/2})$  time.



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## Proof.

- Lemma 1. Each phase of normal augmentations takes O(|E|) time.
- Lemma 2. After  $|V|^{1/2}$  phases,  $val(f) \ge val(f^*) |V|^{1/2}$ .
- Lemma 3. After  $\leq |V|^{1/2}$  additional augmentations, flow is optimal.



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*Proof.* Each augmentation increases flow value by at least 1.



### Phase of normal augmentations.

- Construct level graph  $L_G$ .
- Start at s, advance along an edge in  $L_G$  until reach t or get stuck.
- If reach t, augment flow; update  $L_G$ ; and restart from s.
- If get stuck, delete node from  $L_G$  and go to previous node.

#### construct level graph





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## Proof.

- O(|E|) to create level graph  $L_G$ .
- O(1) per edge (each edge involved in at most one advance, retreat, and augmentation).
- O(1) per node (each node deleted at most once)



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Let  $A = \{v : \ell(v) < h\} \cup \{v : \ell(v) = h \text{ and } v \text{ has } \leq 1 \text{ outgoing residual edge} \}$ .
## **Computational Geometry**



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Let  $A = \{v : \ell(v) < h\} \cup \{v : \ell(v) = h \text{ and } v \text{ has } \leq 1 \text{ outgoing residual edge} \}$ .

 $\operatorname{cap}_{f}(A, B) \le |V_{h}| \le |V|^{1/2} \Rightarrow val(f) \ge \operatorname{val}(f^{*}) - |V|^{1/2}$ 

# **Computational Geometry**









### Theorem (Even–Tarjan 1975)

In simple unit-capacity networks, Dinitz' algorithm computes a maximum flow in  $O(|E||V|^{1/2})$  time.

### Proof.

- Lemma 1. Each phase take O(|E|) time.
- Lemma 2. After  $|V|^{1/2}$  phase,  $\operatorname{val}(f) \ge \operatorname{val}(f^*) |V|^{1/2}$
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- Lemma 3. After  $\leq |V|^{1/2}$  additional augmentations.

### Corollary

Dinitz' algorithm computes maximum-cardinality bipartite matching in  $O(|E||V|^{1/2})$  time.

# **Disjoint Paths**

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Edge-disjoint paths problem. Given a digraph G = (V, E) and two nodes s and t, find the max number of edge-disjoint  $s \rightsquigarrow t$  paths.



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Max-flow formulation. Assign unit capacity to every edge.



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• Let  $P_1, \ldots, P_k$  be k edge-disjoint  $s \rightsquigarrow t$  paths in G.



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### *Proof.* $\Rightarrow$

- Let  $P_1, \ldots, P_k$  be k edge-disjoint  $s \rightsquigarrow t$  paths in G.
- Set  $f(e) = \begin{cases} 1 & \text{edge } e \text{ participates in some path } P_j \\ 0 & \text{otherwise} \end{cases}$



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- Let  $P_1, \ldots, P_k$  be k edge-disjoint  $s \rightsquigarrow t$  paths in G.
- Set  $f(e) = \begin{cases} 1 & \text{edge } e \text{ participates in some path } P_j \\ 0 & \text{otherwise} \end{cases}$
- Since paths are edge-disjoint, *f* is a flow of value *k*.



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Proof. <del>(</del>



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### Proof. ←

- Let f be an integral flow in G' of value k.
- Consider edge (s, u) with f(s, u) = 1.
  - by flow conservation, there exists an edge (u, v) with f(u, v) = 1.
  - continue until reach *t*, always choosing a new edge
- Produces k (not necessarily simple) edge-disjoint paths.



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Can solve edge-disjoint paths problem via max-flow formulation.

#### Proof.

- Integrality theorem  $\Rightarrow$  there exists a max flow  $f^*$  in G' that is integral.
- 1-1 correspondence  $\Rightarrow f^*$  corresponds to max number of edge-disjoint  $s \rightsquigarrow t$  paths in G.

## **Network Connectivity**



#### Definition

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A set of edges  $F \subseteq E$  disconnects t from s if every  $s \rightsquigarrow t$  path uses at least one edge in F.

Network connectivity. Given a digraph G = (V, E) and two nodes s and t, find minimal number of edges whose removal disconnects t from s.



### Theorem (Menger 1927)

The max number of edge-disjoint  $s \rightsquigarrow t$  paths equals the min number of edges whose removal disconnects t from s.



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### *Proof.* $\leq$

- Suppose the removal of  $F \subseteq E$  disconnects t from s, and |F| = k.
- Every  $s \rightsquigarrow t$  path uses at least one edge in F.
- Hence, the number of edge-disjoint paths is  $\leq k$ .



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### *Proof.* $\geq$

- Suppose max number of edge-disjoint  $s \rightsquigarrow t$  paths is k.
- Then value of max flow = k.
- Max-flow min-cut theorem  $\Rightarrow$  there exists a cut (A, B) of capacity k.
- Let *F* be set of edges going from *A* to *B*.
- |F| = k and disconnects *t* from *s*.

# **Referred Materials**

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## **Referred Materials**



• Content of this lecture comes from Section 7.5 in [KT05].