



## Design and Analysis of Algorithms (XX)

Polynomial Time Approximation Scheme

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# Approximation Scheme

Let  $\Pi$  be an NP-hard optimization problem with objective function  $f_{\Pi}$ . We will say that algorithm  $\mathcal{A}$  is an approximation scheme for  $\Pi$  if on input  $(I, \epsilon)$ , where  $I$  is an instance of  $\Pi$  and  $\epsilon > 0$  is an error parameter, it outputs a solution  $s$  such that:

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- $f_{\Pi}(I, s) \leq (1 + \epsilon) \cdot \text{OPT}$  if  $\Pi$  is a **minimization** problem.
- $f_{\Pi}(I, s) \geq (1 - \epsilon) \cdot \text{OPT}$  if  $\Pi$  is a **maximization** problem.

$\mathcal{A}$  will be said to be a **polynomial-time approximation scheme**, abbreviated **PTAS**, if for each fixed  $\epsilon > 0$ , its running time is bounded by a **polynomial** in the size of instance  $I$ .

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If we require that the running time of  $\mathcal{A}$  be bounded by a **polynomial** in the size of instance  $I$  and  $1/\epsilon$ , then  $\mathcal{A}$  will be said to be a **fully polynomial-time approximation scheme**, abbreviated **FPTAS**.



# Knapsack: Problem Statement

## KNAPSACK

Given a set  $S = \{a_1, \dots, a_n\}$  of **objects**, with specified **sizes** and **profits**,  $\text{size}(a_i) \in \mathbb{Z}^+$  and  $\text{profit}(a_i) \in \mathbb{Z}^+$ , and a “**knapsack capacity**”  $B \in \mathbb{Z}^+$ , find a subset of objects whose total size is bounded by  $B$  and total profit is **maximized**.



## An Example

Objects	A	B	C	D	E
Sizes	7	2	9	3	1
Profits	3	2	3	1	2

Knapsack size:  $B$

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# Dynamic Programming

## Knapsack with Repetition

$$K(w) = \max_{a_i: \text{size}(a_i) \leq w} \{K(w - \text{size}(a_i)) + \text{profit}(a_i)\}$$

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$$K(w, j) = \max\{K(w - \text{size}(a_j), j - 1) + \text{profit}(a_j), K(w, j - 1)\}$$

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For each  $i \in \{1, \dots, n\}$  and  $p \in \{1, \dots, nP\}$ , let  $S_{i,p}$  denote a **subset** of  $\{a_1, \dots, a_i\}$  whose **total profit** is exactly  $p$  and whose **total size** is minimized.

# Dynamic Programming

$A(i, p)$  denote the size of the set  $S_{i,p}$  ( $A(i, p) = \infty$  if no such set exists).

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The following recurrence helps compute all **values**  $A(i, p)$  in  $O(n^2P)$  time:

$$A(i + 1, p) = \begin{cases} \min\{A(i, p), \text{size}(a_{i+1}) + A(i, p - \text{profit}(a_{i+1}))\} & \text{if } \text{profit}(a_{i+1}) \leq p \\ A(i, p) & \text{otherwise} \end{cases}$$

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The **maximum profit** achievable by objects of total size bounded by  $B$  is  $\max\{p \mid A(n, p) \leq B\}$ .

## An Example

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	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
1	$\infty$	$\infty$	7	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
2	$\infty$	2	7	$\infty$	9	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
3	$\infty$	2	7	$\infty$	9	16	$\infty$	18	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
4	3	2	5	10	9	14	19	18	21	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
5	3	1	4	3	8	11	10	13	20	19	22	$\infty$	$\infty$	$\infty$	$\infty$

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In **FPTAS** we will ignore a certain number of least significant bits of **profits** of objects (depending on  $\epsilon$ ), so that the modified profits can be viewed as numbers **bounded** by a polynomial in  $n$  and  $1/\epsilon$ .

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- 3 With these as profits of objects, using the **dynamic programming** algorithm, find the most profitable set, say  $S'$ .
- 4 Output  $S'$ .

## Lemma

Let  $A$  denote the set output by the algorithm. Then

$$\text{profit}(A) \geq (1 - \epsilon) \cdot \text{OPT}.$$

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Therefore,

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Therefore,

$$\begin{aligned} \text{profit}(S) &\geq K \cdot \text{profit}'(S) \geq K \cdot \text{profit}'(O) \\ &\geq \text{profit}(O) - nK = \text{OPT} - \epsilon P \geq (1 - \epsilon) \cdot \text{OPT} \end{aligned}$$

# Analysis

By previous Lemma, the solution found is within  $(1 - \epsilon)$  factor of **OPT**. Since the running time of the algorithm is

$$O(n^2 \lfloor \frac{P}{K} \rfloor) = O(n^2 \lfloor \frac{n}{\epsilon} \rfloor)$$

which is **polynomial** in  $n$  and  $1/\epsilon$ , thus it is a **FPTAS** for knapsack.





# Bin Packing: Problem Statement

## BIN PACKING

Given  $n$  items with sizes  $a_1, \dots, a_n \in (0, 1]$ , find a packing in **unit-sized bins** that **minimizes the number** of bins used.

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- It attempts to put the next item,  $a_i$ , in one of these bins, in this order.
- If  $a_i$  does not fit into any of these bins, it opens a **new** bin  $B_{k+1}$ , and puts  $a_i$  in it.





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Therefore,

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Since the sum of the item sizes is a **lower bound** on  $\text{OPT}$ ,  $m - 1 < 2 \cdot \text{OPT}$ , i.e.,  $m \leq 2 \cdot \text{OPT}$ .

## A Hardness Result

For any  $\epsilon > 0$ , there is no **approximation algorithm** having a guarantee of  $3/2 - \epsilon$  for the bin packing problem, assuming **P = NP**.

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If there were such an algorithm, then the **NPC problem** of deciding if there is a way to partition  $n$  nonnegative numbers  $a_1, \dots, a_n$  into two sets, each adding up to  $1/2 \sum_i a_i$ .

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The answer to this question is “yes” iff the  $n$  items can be packed in 2 bins of size  $1/2 \sum_i a_i$ .

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The answer to this question is “**yes**” iff the  $n$  items can be packed in 2 bins of size  $1/2 \sum_i a_i$ .

If the answer is “**yes**” the  $3/2 - \epsilon$  factor algorithm will have to give an optimal packing.



**APTAS**

An **asymptotic polynomial-time approximation scheme (APTAS)** is a family of algorithm  $\{A_\epsilon\}$  along with a constant  $c$  where there is an algorithm  $A_\epsilon$  for each  $\epsilon > 0$  such that  $A_\epsilon$  returns a solution of value **at most**  $(1 + \epsilon)\text{OPT} + c$  for minimization problems.

## An APTAS for Bin-Packing

For any  $\epsilon$ ,  $0 < \epsilon \leq 1/2$ , there is an algorithm  $A_\epsilon$  that runs in time polynomial in  $n$  and finds a packing using at most  $(1 + 2\epsilon)\text{OPT} + 1$  bins.

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We will introduce the algorithm in three steps.

### Lemma

Let  $\epsilon > 0$  be fixed, and let  $K$  be a fixed nonnegative integer. Consider the restriction of the bin packing problem to instances in which each item is *of size at least  $\epsilon$*  and the number of distinct item sizes is  $K$ . There is *a polynomial time algorithm that optimally solves this restricted problem*.

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The number of items in a bin is bounded by  $\lfloor 1/\epsilon \rfloor$ . Denote this by  $M$ . Therefore, the number of different bin types is bounded by

$$R = \binom{M + K}{M}$$

which is a **large** constant.

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The total number of bins used is at most  $n$ . Therefore, the number of possible feasible packings is bounded by

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**Enumerating** them and picking the best packing gives the optimal answer.



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## Removing the Restriction of $K$

### Lemma

Let  $\epsilon > 0$  be fixed. Consider the restriction of the bin packing problem to instances in which each item is of size at least  $\epsilon$ . There is a *polynomial time approximation algorithm* that solves this restricted problem *within a factor of  $(1 + \epsilon)$* .

## Removing the Restriction of $K$

Let  $I$  denote the given instance. Sort the  $n$  items by **increasing size**, and partition them into  $K = \lceil 1/\epsilon^2 \rceil$  groups each having at most  $Q = \lfloor n\epsilon^2 \rfloor$  items. Notice that two groups may contain items of the same size.

# Removing the Restriction of $K$



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We will show that

$$\text{OPT}(J) \leq (1 + \epsilon)\text{OPT}(I)$$

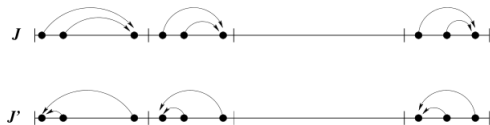
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$$\text{OPT}(J) \leq \text{OPT}(J') + Q \leq \text{OPT}(I) + Q$$

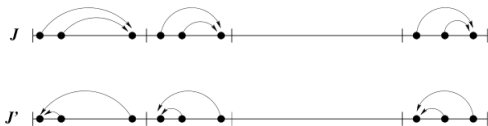
Let us construct another instance, say  $J'$ , by **rounding down** the size of each item to that of the smallest item in its group.

Clearly  $\text{OPT}(J') \leq \text{OPT}(I)$ .

The crucial observation is that a packing for instance  $J$  yields a packing for all but the largest  $Q$  items of instance  $J'$ . Therefore,

$$\text{OPT}(J) \leq \text{OPT}(J') + Q \leq \text{OPT}(I) + Q$$

Since each item in  $I$  has size at least  $\epsilon$ ,  $\text{OPT}(I) \geq n\epsilon$ . Therefore  $Q = \lfloor n\epsilon^2 \rfloor \leq \epsilon \text{OPT}(I)$ . Hence,  $\text{OPT}(J) \leq (1 + \epsilon)\text{OPT}(I)$ .



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- Let  $I$  denote the given instance, and  $I'$  denote the instance obtained by discarding items of size  $< \epsilon$  from  $I$ .
- By previous lemma, we can find a packing for  $I'$  using at most  $(1 + \epsilon)\text{OPT}(I')$  bins.
- Next, we start packing the small items (of size  $< \epsilon$ ) in a **First-Fit manner** in the bins opened for packing  $I$ . Additional bins are opened if an item does not fit into any of the already open bins.



If no additional bins are needed, then we have a packing in  $(1 + \epsilon)\text{OPT}(I') \leq (1 + \epsilon)\text{OPT}(I)$  bins.



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Therefore, the sum of the item sizes in  $I$  is at least  $(M - 1)(1 - \epsilon)$ . Since this is a lower bound on  $\text{OPT}$ , we get



$$M \leq \frac{\text{OPT}}{(1 - \epsilon)} + 1 \leq (1 + 2\epsilon)\text{OPT} + 1$$

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Hence, for each value of  $\epsilon$ ,  $0 < \epsilon \leq 1/2$ , we have a polynomial time algorithm achieving a guarantee of  $(1 + 2\epsilon)\text{OPT} + 1$ .

# Summary of Algorithm

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Algorithm  $A_\epsilon$  is summarized below.



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## Algorithm

1. Remove items of size  $< \epsilon$ .
2. Round to obtain constant number of item sizes.
3. Find optimal packing.
4. Use this packing for original item sizes.
5. Pack items of size  $< \epsilon$  using First-Fit.



## Referred Materials

Content of this lecture comes from Chapter 8 and 9 in [Vaz04], and Section 3.3 in [WS11].

Suggest to read Chapter 10 in [Vaz04] and Chapter 3 in [WS11].