

Polynomial Hierarchy

“A polynomial-bounded version of Kleene’s Arithmetic Hierarchy becomes trivial if $\mathbf{P} = \mathbf{NP}$.”

Karp, 1972



Larry Stockmeyer and Albert Meyer introduced polynomial hierarchy.

1. Larry Stockmeyer and Albert Meyer. The Equivalence Problem for Regular Expressions with Squaring Requires Exponential Space. SWAT'72.

Synopsis

1. Meyer-Stockmeyer's Polynomial Hierarchy
2. Stockmeyer-Wrathall Characterization
3. Chandra-Kozen-Stockmeyer Theorem
4. Infinite Hierarchy Conjecture
5. Time-Space Trade-Off

Meyer-Stockmeyer's Polynomial Hierarchy

Problem Beyond NP

Meyer and Stockmeyer observed that MINIMAL does not seem to have short witnesses.

$$\text{MINIMAL} = \{\varphi \mid \varphi \text{ DNF} \wedge \forall \text{ DNF } \psi. |\psi| < |\varphi| \Rightarrow \exists u. \neg(\psi(u) \Leftrightarrow \varphi(u))\}.$$

Notice that $\overline{\text{MINIMAL}}$ can be solved by an NDTM that queries SAT a polynomial time.

In other words, $\overline{\text{MINIMAL}} \in \mathbf{NP}^{\mathbf{NP}}$.

$$\mathbf{P}^{\mathcal{C}} = \bigcup_{A \in \mathcal{C}} \mathbf{P}^A,$$
$$\mathbf{NP}^{\mathcal{C}} = \bigcup_{A \in \mathcal{C}} \mathbf{NP}^A.$$

Meyer-Stockmeyer's Definition

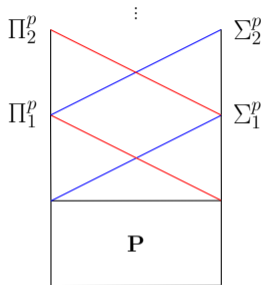
The complexity classes $\Sigma_i^P, \Pi_i^P, \Delta_i^P$ are defined as follows:

$$\begin{aligned}\Sigma_0^P &= \mathbf{P}, \\ \Sigma_{i+1}^P &= \mathbf{NP}^{\Sigma_i^P}, \\ \Delta_{i+1}^P &= \mathbf{P}^{\Sigma_i^P}, \\ \Pi_i^P &= \mathbf{co-}\Sigma_i^P.\end{aligned}$$

The following hold:

- ▶ $\Sigma_i^P \subseteq \Delta_{i+1}^P \subseteq \Sigma_{i+1}^P$,
- ▶ $\Pi_i^P \subseteq \Delta_{i+1}^P \subseteq \Pi_{i+1}^P$.

Notice that $\Pi_{i+1}^P = \mathbf{coNP}^{\Sigma_i^P}$ by definition.



The **polynomial hierarchy** is the complexity class $\mathbf{PH} = \bigcup_{i \geq 0} \Sigma_i^P$.

Natural Problem in the Second Level

“Synthesizing circuits is exceedingly difficult. It is even more difficult to show that a circuit found in this way is the most economical one to realize a function. The difficulty springs from the large number of essentially different networks available.”

Claude Shannon, 1949

Umans showed in 1998 that the following language is Σ_2^P -complete.

$$\text{MIN-DNF} = \{ \langle \varphi, k \rangle \mid \varphi \text{ DNF} \wedge \exists \text{ DNF } \psi. |\psi| \leq k \wedge \forall u. \psi(u) \Leftrightarrow \varphi(u) \}.$$

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- ▶ $\overline{\text{MIN-DNF}}$ is the problem referred to by Shannon.
 - ▶ The complexity of MINIMAL, as well as $\overline{\text{MINIMAL}}$, is not known.

Natural Problem in the Second Level

TERMWISE MIN DNF:

Given a DNF $\varphi = \bigvee_{i \in [m]} \varphi_i$ and an integer k , is there a DNF $\varphi' = \bigvee_{i \in [m]} \varphi'_i$ of size at most k such that for all $i \in [m]$ the variables that appear in φ'_i also appear in φ_i ?

This is another Σ_2^P -complete problem.

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1. C. Umans. The Minimum Equivalent DNF Problem and Shortest Implicants. JCSS, 597-611, 2001. Preliminary version in FOCS 1998.

Natural Problem in the Second Level

EXACT INDSET refers to the following problem:

$\{\langle G, k \rangle \mid \text{the largest independent sets of } G \text{ are of size } k\}$.

It is in Δ_2^P .

Stockmeyer-Wrathall Characterization

In 1976, Stockmeyer defined Polynomial Hierarchy in terms of alternation of quantifier and Wrathall proved that it is equivalent to the original definition.

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1. Larry Stockmeyer. The Polynomial-Time Hierarchy. Theoretical Computer Science, 3:1-22, 1976.
 2. Celia Wrathall. Complete Sets and the Polynomial-Time Hierarchy. Theoretical Computer Science. 3:23-33, 1976.

Logical Characterization

The following result generalizes the logical characterization of NP problems.

Theorem. Suppose $i \geq 1$.

- ▶ $L \in \Sigma_i^P$ iff there exists a P-time TM M and a polynomial q such that for all $x \in \{0, 1\}^*$,

$$x \in L \text{ iff } \exists u_1 \in \{0, 1\}^{q(|x|)} \forall u_2 \in \{0, 1\}^{q(|x|)} \dots Q_i u_i \in \{0, 1\}^{q(|x|)}. M(x, \tilde{u}) = 1.$$

- ▶ $L \in \Pi_i^P$ iff there exists a P-time TM M and a polynomial q such that for all $x \in \{0, 1\}^*$,

$$x \in L \text{ iff } \forall u_1 \in \{0, 1\}^{q(|x|)} \exists u_2 \in \{0, 1\}^{q(|x|)} \dots Q_i u_i \in \{0, 1\}^{q(|x|)}. M(x, \tilde{u}) = 1.$$

1. Celia Wrathall. Complete Sets and the Polynomial-Time Hierarchy. Theoretical Computer Science. 3:23-33, 1976.

Proof of Wrathall Theorem: \Leftarrow

Let \mathbb{M} be a P-time TM and q a polynomial such that $x \in L$ if and only if

$$\exists u_1 \in \{0, 1\}^{q(|x|)} \dots \exists u_{i+1} \in \{0, 1\}^{q(|x|)}. \mathbb{M}(x, u_1, \dots, u_{i+1}) = 1.$$

Given x an NDTM guesses a u_1 and asks if the following is true

$$\forall u_2 \in \{0, 1\}^{q(|x|)} \dots \exists u_{i+1} \in \{0, 1\}^{q(|x|)}. \mathbb{M}(x, u_1, \dots, u_{i+1}) = 1.$$

By induction hypothesis the above formula can be evaluated by querying a Σ_i^P oracle.

Proof of Wrathall Theorem: \Rightarrow

Let L be decided by a P-time NDTM \mathbb{N} with access to some oracle $A \in \Sigma_i^P$. Now by Cook-Levin Theorem, $x \in L$ if and only if

$\exists \tilde{z}. \exists c_1, \dots, c_m, a_1, \dots, a_k. \exists u_1, \dots, u_k. (\mathbb{N} \text{ accepts } x \text{ using choices } c_1, \dots, c_m$
and answers a_1, \dots, a_k to the queries $u_1, \dots, u_k) \wedge (\bigwedge_{i \in [k]} a_i = 1 \Rightarrow u_i \in A)$
 $\wedge (\bigwedge_{i \in [k]} a_i = 0 \Rightarrow u_i \in \overline{A}),$

where \tilde{z} are introduced by the Cook-Levin reduction. We are done by **induction**.

Let $\Sigma_i\text{SAT}$ be the subset of TQBF that consists of all tautologies of the following form

$$\exists u_1 \forall u_2 \dots Q_i u_i \cdot \varphi(u_1, \dots, u_i),$$

where $\varphi(u_1, \dots, u_i)$ is a **propositional** formula.

Theorem (Meyer and Stockmeyer, 1972). $\Sigma_i\text{SAT}$ is Σ_i^P -complete.

Proof.

The fact $\Sigma_i\text{SAT} \in \Sigma_i^P$ follows from the previous theorem.

The completeness is defined with regards to the Karp reduction. □

Theorem (Stockmeyer, Wrathall, 1976). $\mathbf{PH} \subseteq \mathbf{PSPACE}$.

Chandra-Kozen-Stockmeyer Theorem



Ashok Chandra, Dexter Kozen and Larry Stockmeyer introduced Alternating Turing Machines that give alternative characterization of complexity classes.

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1. Alternation. *Journal of the ACM*, 28(1):114-133, 1981.

Alternating Turing Machine

An **Alternating Turing Machine** (ATM) is an **NDTM** in which every state is labeled by an element of $\{\exists, \forall, \text{halt}\}$.

We say that an ATM \mathbb{A} **accepts** x if there is a subtree Tr of the execution tree of $\mathbb{A}(x)$ satisfying the following:

- ▶ The initial configuration is in Tr .
 - ▶ All leaves of Tr are labeled by **accept**.
 - ▶ If a node labeled by \forall is in Tr , both children are in Tr .
 - ▶ If a node labeled by \exists is in Tr , one of its children is in Tr .
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NDTM's are ATM's.

Complexity via ATM

For every $T: \mathbf{N} \rightarrow \mathbf{N}$, we say that an ATM \mathbb{A} runs in $T(n)$ -time if for every input $x \in \{0, 1\}^*$ and for all nondeterministic choices, \mathbb{A} halts after at most $T(|x|)$ steps.

- ▶ **ATIME**($T(n)$) contains L if there is a $cT(n)$ -time ATM \mathbb{A} for some constant c such that, for all $x \in \{0, 1\}^*$, $x \in L$ if and only if $\mathbb{A}(x) = 1$.
- ▶ **ASPACE**($S(n)$) is defined analogously.

Example of ATM

TQBF is solvable by an ATM in quadratic time and linear space.

Complexity Class via ATM

$$\mathbf{AL} = \mathbf{ASPACE}(\log n),$$

$$\mathbf{AP} = \bigcup_{c>0} \mathbf{ATIME}(n^c),$$

$$\mathbf{APSPACE} = \bigcup_{c>0} \mathbf{ASPACE}(n^c),$$

$$\mathbf{AEXP} = \bigcup_{c>0} \mathbf{ATIME}(2^{n^c}),$$

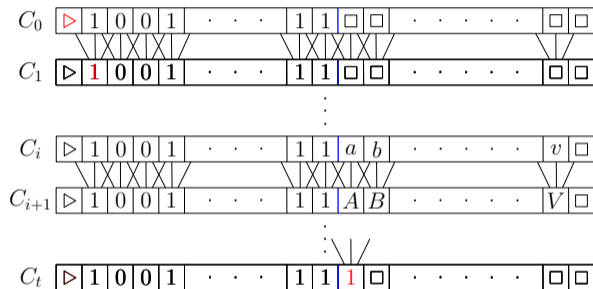
$$\mathbf{AEXPSPACE} = \bigcup_{c>0} \mathbf{ASPACE}(2^{n^c}).$$

Theorem. Assume that the relevant time/space functions are constructible.

1. $\mathbf{NSPACE}(S(n)) \subseteq \mathbf{ATIME}(S^2(n))$.
2. $\mathbf{ATIME}(T(n)) \subseteq \mathbf{SPACE}(T(n))$.
3. $\mathbf{ASPACE}(S(n)) \subseteq \bigcup_{c>0} \mathbf{TIME}(c^{S(n)})$.
4. $\mathbf{TIME}(T(n)) \subseteq \mathbf{ASPACE}(\log T(n))$.

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1. Savitch's proof. Recursive calls are implemented using \forall -state. We need to assume that $S(n)$ is time constructible.
 2. Traversal of configuration tree. Counters of length $T(n)$.
 3. Depth first traversal of configuration graph.
 4. Backward guessing (\exists) and parallel checking (\forall) in the configuration path.

Configuration Path, Logic Characterization of Computation



Backward guessing using \exists state and parallel checking using \forall state.

Chandra-Kozen-Stockmeyer Theorem

$$\begin{array}{ccccccc} \mathbf{AL} & \subseteq & \mathbf{AP} & \subseteq & \mathbf{APSPACE} & \subseteq & \mathbf{AEXP} \dots \\ = & & = & & = & & = \dots \\ \mathbf{L} & \subseteq & \mathbf{P} & \subseteq & \mathbf{PSPACE} & \subseteq & \mathbf{EXP} \subseteq \mathbf{EXPSPACE} \dots \end{array}$$

Bounded Alternation

$L \in \Sigma_i \mathbf{TIME}(T(n)) / \Pi_i \mathbf{TIME}(T(n))$ if

L is accepted by an $O(T(n))$ -time ATM \mathbb{A} with q_{start} labeled by \exists/\forall , and on every path the machine \mathbb{A} may alternate at most $i - 1$ times.

Polynomial Hierarchy Defined via ATM

Theorem. For every $i \geq 1$, the following hold:

$$\Sigma_i^P = \bigcup_{c>0} \Sigma_i \mathbf{TIME}(n^c),$$

$$\Pi_i^P = \bigcup_{c>0} \Pi_i \mathbf{TIME}(n^c).$$

Use the logical characterization.

Infinite Hierarchy Conjecture

Theorem. If $\mathbf{NP} = \mathbf{P}$ then $\mathbf{PH} = \mathbf{P}$.

Suppose $\Sigma_i^{\mathbf{P}} = \mathbf{P}$. Then $\Sigma_{i+1}^{\mathbf{P}} = \mathbf{NP}^{\Sigma_i^{\mathbf{P}}} = \mathbf{NP}^{\mathbf{P}} = \mathbf{NP} = \mathbf{P}$.

Theorem (Meyer and Stockmeyer, 1972). For each $i \geq 1$, if $\Sigma_i^P = \Pi_i^P$ then $\mathbf{PH} = \Sigma_i^P$.

Suppose $\Sigma_k^P = \Pi_k^P$. Then $\Sigma_{k+1}^P = \Sigma_k^P = \Pi_k^P = \Pi_{k+1}^P$, confer the **proof** on page 16.

Theorem. If there exists a language L that is **PH**-complete with regards to Karp reduction, then some i exists such that $\mathbf{PH} = \Sigma_i^P$.

If such a language L exists, then $L \in \Sigma_i^P$ for some i . Consequently every language in **PH** is Karp reducible to L .

Theorem. If $\mathbf{PH} = \mathbf{PSPACE}$, then \mathbf{PH} collapses.

If $\mathbf{PH} = \mathbf{PSPACE}$, then \mathbf{TQBF} would be \mathbf{PH} -complete.

Infinite Hierarchy Conjecture. Polynomial Hierarchy does not collapse.

Many results in complexity theory take the following form

“If something is not true, then the polynomial hierarchy collapses”.

Time-Space Trade-Off

To summarize our current understanding of NP-completeness from an algorithmic point of view, it suffices to say that at the moment we **cannot** prove **either** of the following statements:

SAT \notin **TIME**(n),

SAT \notin **SPACE**($\log n$).

We can however prove that SAT cannot be solved by any TM that runs in both linear time and logspace. Notationally,

$$\text{SAT} \notin \mathbf{TISP}(n, \log n).$$

Suppose $S, T : \mathbf{N} \rightarrow \mathbf{N}$. A problem is in

$$\mathbf{TISP}(T(n), S(n))$$

if it is decided by a TM that on every input x takes at most $O(T(|x|))$ time and uses at most $O(S(|x|))$ space.

Time-Space Tradeoff for SAT

Theorem. $\text{SAT} \notin \mathbf{TISP}(n^{1.1}, n^{0.1})$.

We show that $\mathbf{NTIME}(n) \not\subseteq \mathbf{TISP}(n^{1.2}, n^{0.2})$, which implies the theorem for the following reason:

1. Using Cook-Levin reduction a problem $L \in \mathbf{NTIME}(n)$ is reduced to a formula, every bit of the formula can be computed in **logarithmic** space and **polylogarithmic** time.
2. If $\text{SAT} \in \mathbf{TISP}(n^{1.1}, n^{0.1})$, then F could be computed in $\mathbf{TISP}(n^{1.1} \text{polylog}(n), n^{0.1} \text{polylog}(n))$.
3. But then one would have $L \in \mathbf{TISP}(n^{1.2}, n^{0.2})$.

The proof of $\mathbf{NTIME}(n) \not\subseteq \mathbf{TISP}(n^{1.2}, n^{0.2})$ is given next.

The Cook-Levin reduction makes use of the configuration circuit.

$$\mathbf{TISP}(n^{12}, n^2) \subseteq \Sigma_2 \mathbf{TIME}(n^8).$$

Suppose L is decided by \mathbb{M} using n^{12} time and n^2 space.

- ▶ Given input x a node of $G_{\mathbb{M},x}$ is of length $O(n^2)$.
- ▶ $x \in L$ iff C_{accept} can be reached from C_{start} in n^{12} steps.
- ▶ There is such a path iff **there exist** n^6 nodes C_1, \dots, C_{n^6} , whose total length is $O(n^8)$, such that, **for all** $i \in \{1, \dots, n^6\}$, C_i can be reached from C_{i-1} in $O(n^6)$ -steps.
- ▶ The latter condition can be verified in $O(n^6 \log n)$ -time by resorting to a universal machine.

It is now easy to see that $L \in \Sigma_2 \mathbf{TIME}(n^8)$.

If $\mathbf{NTIME}(n) \subseteq \mathbf{TIME}(n^{1.2})$ then $\Sigma_2\mathbf{TIME}(n^8) \subseteq \mathbf{NTIME}(n^{9.6})$.

Suppose $L \in \Sigma_2\mathbf{TIME}(n^8)$. Then some c, d and $(O(n^8))$ -time TM \mathbb{M} exist such that $x \in L$ iff

$$\exists u \in \{0, 1\}^{c|x|^8}. \forall v \in \{0, 1\}^{d|x|^8}. \mathbb{M}(x, u, v) = 1. \quad (1)$$

Given \mathbb{M} one can design a **linear** time **ND**TM \mathbb{N} that given $x \circ u$ returns 1 iff $\exists v \in \{0, 1\}^{d|x|^8}. \mathbb{M}(x, u, v) = 0$.

- ▶ By assumption there is some $O(n^{1.2})$ -time TM \mathbb{D} such that $\mathbb{D}(x, u) = 1$ iff $\exists v \in \{0, 1\}^{d|x|^8}. \mathbb{M}(x, u, v) = 0$.
- ▶ Consequently $\overline{\mathbb{D}}(x, u) = 1$ iff $\forall v \in \{0, 1\}^{d|x|^8}. \mathbb{M}(x, u, v) = 1$.

It follows that there is an $O(n^{9.6})$ time NDTM \mathbb{C} such that

$$\mathbb{C}(x) = 1 \text{ iff } \exists u \in \{0, 1\}^{c|x|^8}. \overline{\mathbb{D}}(x, u) = 1 \text{ iff (1) holds iff } x \in L,$$

implying that $L \in \mathbf{NTIME}(n^{9.6})$.

$$\begin{array}{lcl}
\mathbf{NTIME}(n) & \subseteq & \mathbf{TISP}(n^{1.2}, n^{0.2}), \text{ hypothesis} \\
& \Downarrow & \\
\mathbf{NTIME}(n^{10}) & \subseteq & \mathbf{TISP}(n^{12}, n^2) \\
& \Downarrow & \\
\mathbf{NTIME}(n^{10}) & \subseteq & \Sigma_2 \mathbf{TIME}(n^8), \text{ alternation introduction} \\
& \Downarrow & \\
\mathbf{NTIME}(n^{10}) & \subseteq & \mathbf{NTIME}(n^{9.6}), \text{ alternation elimination,} \\
& \text{but} & \\
\mathbf{NTIME}(n^{9.6}) & \subsetneq & \mathbf{NTIME}(n^{10}), \text{ Hierarchy Theorem.}
\end{array}$$

Proof by Indirect Diagonalization

Suppose we want to prove $\mathbf{NTIME}(n) \not\subseteq \mathbf{TISP}(T(n), S(n))$.

1. Assume $\mathbf{NTIME}(n) \subseteq \mathbf{TISP}(T(n), S(n))$.
2. Derive unlikely inclusions of complexity classes.
 - ▶ **Introduce alternation** to speed up space bound computation.
 - ▶ **Eliminate alternation** using hypothesis.
3. Derive a contradiction using a **diagonalization** argument.

Lance Fortnow proved the first time-space lower bound. A survey on the time-space lower bounds for satisfiability is given by Dieter van Melkebeek.

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1. Lance Fortnow. Time-Space Tradeoffs for Satisfiability. *Journal of Computer and System Sciences*, 60:337-353, 2000.
 2. Dieter van Melkebeek. A Survey of Lower Bounds for Satisfiability and Related Problems. *Foundations and Trends in Theoretical Computer Science*, 2:197-303, 2007.